

# A layman's note on a class of frequentist hypothesis testing problems

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## Abstract

It is observed that for testing between simple hypotheses where the cost of Type I and Type II errors can be quantified, it is better to let the optimization choose the test size.

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## I. HYPOTHESIS TESTING

Let  $(X, \mathcal{F}, \mu)$  be a  $\sigma$ -finite measure space and let  $\mathcal{P}$  be the family of probability measures  $\mathbb{P}$  on  $(X, \mathcal{F})$  which are absolutely continuous with respect to  $\mu$  so that, for  $A \in \mathcal{F}$ ,

$$\mathbb{P}(A) = \int_A p(x) d\mu.$$

Here  $p = d\mathbb{P}/d\mu$  is the *density* (Radon-Nikodym derivative) of  $\mathbb{P}$  with respect to  $\mu$ . We are mostly interested in two cases: The first is when  $X$  is a Euclidean space  $\mathbb{R}^N$  equipped with the Borel  $\sigma$ -field and  $\mu$  is Lebesgue measure. The second is when  $X = \mathbb{Z}^N$  or  $X = \mathbb{N}^N$  and  $\mu$  is counting measure on all subsets of  $X$ . This allows us treat probability densities and discrete probability distributions simultaneously.

Let  $\mathbb{P}_0, \mathbb{P}_1 \in \mathcal{P}$  and let  $p_0$  and  $p_1$  be the corresponding densities with respect to  $\mu$ . Let  $(X_1, \dots, X_N)$  be the available sample taking values in  $X$ . We seek a test  $\varphi : X \rightarrow \{0, 1\}$  such that, if  $(x_1, \dots, x_N)$  are the observed values,  $\varphi(x_1, \dots, x_N) = 0$  if we accept  $H_0 = \{\mathbb{P}_0\}$  and  $\varphi(x_1, \dots, x_N) = 1$  if we accept  $H_1 = \{\mathbb{P}_1\}$ . Let  $\mathcal{C}$  be the *critical region*, namely the subset of observations  $x = (x_1, \dots, x_N)$  such that  $\varphi(x_1, \dots, x_N) = 1$ , namely where we reject the null hypothesis, cf. e.g. [1, Chapter 8].

## II. A CLASS OF INFERENCE PROBLEMS

Consider a simple hypothesis testing problem where we can quantify the cost of each error. Namely, if we reject  $H_0$  when it is true we incur the cost  $c_0 > 0$  and if we reject  $H_1$  when it is true we incur the cost  $c_1 > 0$ . This is the case in many applications such as when, on the basis of a sample, we need to decide whether to halt the production of an item which should meet certain required standards. Both producing a whole stock not meeting the requirements or halting the production process when the requirements are met causes certain quantifiable costs. A type *I* error occurs with probability  $\alpha = \mathbb{P}_0(\mathcal{C})$  while a type *II* error occurs with probability  $\beta = \mathbb{P}_1(\mathcal{C}^c)$ . It is then natural to try to minimise the cost

$$J(\mathcal{C}) = c_0 \mathbb{P}_0(\mathcal{C}) + c_1 \mathbb{P}_1(\mathcal{C}^c).$$

This is a simple unconstrained optimisation problem which can be formalized as follows.

**Problem 1** Find a measurable set  $\mathcal{C} \subset X$  such that the following cost function

$$J(\mathcal{C}) = c_0 \mathbb{P}_0(\mathcal{C}) + c_1 \mathbb{P}_1(\mathcal{C}^c) = \int_{\mathcal{C}} [c_0 p_0(x) - c_1 p_1(x)] d\mu + c_1$$

is minimised or, equivalently abusing notation, minimize

$$J(\mathbb{1}_{\mathcal{C}}) = \int_X \mathbb{1}_{\mathcal{C}} [c_0 p_0(x) - c_1 p_1(x)] d\mu$$

where  $\mathbb{1}_{\mathcal{C}}$  is the indicator function of the set  $\mathcal{C}$ .

Let us introduce the set

$$Q = \{f \in L^\infty(X, \mathcal{F}, \mu) | f : X \rightarrow [0, 1]\},$$

and consider the following “relaxed” version of Problem 1:

**Problem 2**

$$\text{Minimize}_{f \in Q} J(f),$$

where

$$J(f) = \int_X f(x) [c_0 p_0(x) - c_1 p_1(x)] d\mu.$$

Observe that the cost function is *linear* in  $f$  and  $Q$  is convex. Thus, this is a convex optimization problem. We recall a few basic facts from convex optimization. Let  $K$  be a convex subset of the vector space  $V$ , let  $F : K \rightarrow \mathbb{R}$  be convex and let  $x_0 \in K$ . Then, the one-sided directional derivative or hemidifferential of  $F$  at  $x_0$  in direction  $x - x_0$

$$F'_+(x_0; x - x_0) := \lim_{\epsilon \searrow 0} \frac{F(x_0 + \epsilon(x - x_0)) - F(x_0)}{\epsilon}$$

exists for every  $x \in K$  (this is a consequence of the monotonicity of the difference quotients).

We record next the characterisation of optimality for convex problems, see e.g. [2, p.66].

**Theorem 3** Let  $K$  be a convex subset of the vector space  $V$  and let  $F : K \rightarrow \mathbb{R}$  be convex. Then,  $x_0 \in K$  is a minimum point for  $F$  over  $K$  if and only if it holds

$$F'_+(x_0; x - x_0) \geq 0, \quad \forall x \in K. \tag{1}$$

We can then apply this result to Problem 2.

**Proposition 4** *The minimum in Problem 1 is attained for*

$$\mathcal{C}^* = \{x \in X \mid c_0 p_0(x) \leq c_1 p_1(x)\}. \quad (2)$$

*Proof.* We apply Theorem 3 to Problem 2 and get that a necessary and sufficient condition for  $f^* \in Q$  to be a minimum point of  $J(f)$  over  $Q$  is

$$J'(f^*; f - f^*) = \int_X [f(x) - f^*(x)] [c_0 p_0(x) - c_1 p_1(x)] d\mu \geq 0, \quad \forall f \in Q. \quad (3)$$

Observe now that  $f^* = \mathbb{1}_{\mathcal{C}^*}$  satisfies (3). Indeed

$$\begin{aligned} & \int_X [f(x) - \mathbb{1}_{\mathcal{C}^*(x)}] [c_0 p_0(x) - c_1 p_1(x)] d\mu \\ = & \int_{\mathcal{C}^*} [f(x) - \mathbb{1}_{\mathcal{C}^*(x)}] [c_0 p_0(x) - c_1 p_1(x)] d\mu + \int_{(\mathcal{C}^*)^c} [f(x) - \mathbb{1}_{\mathcal{C}^*(x)}] [c_0 p_0(x) - c_1 p_1(x)] d\mu = \\ & \int_{\mathcal{C}^*} [f(x) - 1] [c_0 p_0(x) - c_1 p_1(x)] d\mu + \int_{(\mathcal{C}^*)^c} f(x) [c_0 p_0(x) - c_1 p_1(x)] d\mu \geq 0, \end{aligned}$$

since both integrals in the last line are nonnegative. Indeed,  $f(x) - 1 \leq 0$  and, on  $\mathcal{C}^*$ ,  $c_0 p_0(x) - c_1 p_1(x) \leq 0$  imply that the integrand in the first integral is nonnegative. The integrand of the second integral is the product of two nonnegative functions and is therefore also nonnegative. Finally, since  $f^* = \mathbb{1}_{\mathcal{C}^*}$  is an indicator function, it also solves Problem 1.  $\square$

**Remark 5** *We can rewrite the optimal critical region in the familiar form*

$$\mathcal{C}^* = \left\{x \in X \mid \Lambda(x) \geq \frac{c_0}{c_1}\right\}, \quad \Lambda(x) = \frac{p_1(x)}{p_0(x)}. \quad (4)$$

*Thus, the ratio of the two costs  $c_0/c_1$  plays the role of the multiplier associated to the size constraint in the usual Neyman-Pearson approach. The size of the test and its power, are simply*

$$\alpha^* = \mathbb{P}_0 \left( \Lambda(x) \geq \frac{c_0}{c_1} \right), \quad \beta^* = \mathbb{P}_1 \left( \Lambda(x) \geq \frac{c_0}{c_1} \right). \quad (5)$$

### III. EXAMPLE

We illustrate this approach in the simple case of testing the mean of a normal distribution with known variance. Let  $\mu$  be Lebesgue measure on  $\mathbb{R}$ ,  $p_0 = \mathcal{N}(0, 36)$  and  $p_1 = \mathcal{N}(1.2, 36)$ . Suppose  $(x_1, \dots, x_N)$  are the observed values from a random sample and

let  $\bar{x}_N = (1/N) \sum_{i=1}^N x_i$  be the sample mean. Let us fix  $\alpha = 0.05$  and let  $N = 100$ . Then the optimal Neyman-Pearson test has critical region  $\mathcal{C}_{NP} = \{\bar{x}_{100} \geq 0.987\}$ . The corresponding error of the second type is  $\beta = 0.36$ . Since only the ratio  $(c_0/c_1)$  matters in the minimisation of Problem 1, we take from here on  $c_1 = 1$ . Thus applying the Neyman-Pearson approach with tests of size 0.05, we incur the cost

$$J(\mathcal{C}_{NP}) = c_0(0.05) + 0.36.$$

Next, we compare  $J(\mathcal{C}_{NP})$  with  $J(\mathcal{C}^*) = c_0\alpha^* + \beta^*$ , with  $\mathcal{C}^*$  given by (2) and  $\alpha^*$  and  $\beta^*$  given by (5), for different values of  $c_0$  and  $c_1 = 1$ . We get the results of Table I.

TABLE I: Comparison of costs

	$J(\mathcal{C}_{NP})$	$J(\mathcal{C}^*)$
$c_0 = 1$	$0.05 + 0.36 = 0.41$	$0.1587 + 0.1587 = 0.3174$
$c_0 = e$	$2.718 \times 0.05 + 0.36 = 0.495914$	$2.718 \times 0.06681 + 0.30854 = 0.490129$
$c_0 = e^2$	$7.387 \times 0.05 + 0.36 = 0.7293762$	$7.387 \times 0.02275 + 0.5 = 0.668066171$
$c_0 = e^3$	$20.07929 \times 0.05 + 0.36 = 1.3639645$	$20.07929 \times 0.00621 + 0.69 = 0.81469239$

We see that in all cases, as expected since  $\mathcal{C}^*$  gives the minimum cost, fixing  $\alpha$  a priori without considering the costs of type I and II errors, leads to a higher cost. The costs are closer when  $\alpha^*$  is close to 0.05. Indeed, if  $\alpha^*$  happens to be 0.05, given the form (4) of  $\mathcal{C}^*$ , we have  $\mathcal{C}^* = \mathcal{C}_{NP}$ .

In conclusion, when the cost of the two errors is known, it appears wiser to let the optimization determine the size of the test through (5).

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[1] J. C. Kiefer, Introduction to Statistical Inference, Springer-Verlag, 1987.

[2] P. Kosmol, *Optimierung und Approximation*, De Gruyter Lehrbuch, Berlin, 1991.

